

## EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	2	("5404086").PN.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/04/05 19:26
L2	12267	robot\$5.clm.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/04/05 19:26
L3	763	2 and (leg\$5 foot feet).clm.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/04/05 19:27
L4	41	3 and floor near3 (contact\$5 touch\$5).clm.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/04/05 19:32
L5	115532	((displacement distance length proximity) near3 (measur\$5 indicat\$5 test\$4 detect\$4 determin\$4 sens\$4 identi\$6 evaluat\$5 estimat\$5 transducer gauge cell monitor\$4 comput\$5 inspect\$5 meter calculat\$4)).clm.	US-PGPUB; USPAT; EPO; JPO	OR	ON	2006/04/05 19:33
L6	7	4 and 5	US-PGPUB; USPAT; EPO; JPO	OR	ON	2006/04/05 19:34